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This information is current as of April 19, 2024.

*AJNR Am J Neuroradiol* 2013, 34 (7) 1434-1437

doi: <https://doi.org/10.3174/ajnr.A3403>

<http://www.ajnr.org/content/34/7/1434>

# Visualization of the Trochlear Nerve in the Cistern with Use of High-Resolution Turbo Spin-Echo Multisection Motion-Sensitized Driven Equilibrium

M. Kanoto, Y. Toyoguchi, T. Hosoya, A. Oda, and Y. Sugai



## ABSTRACT

**BACKGROUND AND PURPOSE:** The trochlear nerve is so thin that it is rarely observed with MR imaging. Therefore, we used high-resolution MSDE to reliably visualize the cisternal segments of the trochlear nerve.

**MATERIALS AND METHODS:** Participants were 10 healthy young adults (mean age, 24 years), and 20 trochlear nerves were examined. HR-MRC, BS-MRC, and HR-MSDE were performed. A neuroradiologist judged the visibility of the trochlear nerves as 1 of 4 grades (“Excellent,” “Good,” “Fair,” and “Not”) in each MR imaging sequence. The findings were then statistically analyzed with the  $\chi^2$  test.

**RESULTS:** Of all 20 trochlear nerves, 6 with HR-MRC, 13 with BS-MRC, and 18 with HR-MSDE were judged as “Excellent.” CSF flow-related artifacts and vessels in the cistern and cerebellar tentorium in HR-MRC tended to prevent the neuroradiologists from identifying the trochlear nerve. Vessels in the cistern and cerebellar tentorium in BS-MRC also tended to prevent the neuroradiologists from identifying the trochlear nerve. Compared with other sequences, HR-MSDE visualized the trochlear nerve more often. The  $\chi^2$  test revealed statistically significant differences among the 3 MR imaging sequences ( $P < .01$ ). The scan time of HR-MSDE was approximately 1.5–2.2 times longer than that of the other sequences.

**CONCLUSIONS:** HR-MSDE is able to clearly visualize the trochlear nerve and has the same or better ability to delineate the trochlear nerve compared with other MR imaging sequences, though its long scan time does not yet yield practical use.

**ABBREVIATIONS:** BS = balanced sequence; HR = high-resolution; MRC = MR cisternography; MSDE = motion-sensitized driven equilibrium; SAR = specific absorption rate

Trochlear nerve palsy is clinically characterized by vertical diplopia (incomitant hypertropia that increases on tilting of the head toward the paralyzed site [Bielschowsky test]), excyclotropia, and head tilt.<sup>1,2</sup> The trochlear nerve is easily injured by surgery, head trauma, brain herniation, and other insults.<sup>3</sup> Imaging assessment of the trochlear nerve is more difficult than other cranial nerves, as the fourth cranial nerve is much thinner than the other cranial nerves and has a complex course in the basal cisterns.

The trochlear nerve is the only cranial nerve that originates from the mesencephalic dorsum and runs along the cerebellar tentorium as it courses to the cavernous sinus.<sup>4-7</sup> Arteries and veins surround the trochlear nerve in a complicated manner. Given the small size of the nerve and complex cisternal anatomy, it has been difficult to reliably identify the trochlear nerve by MR imaging and other imaging modalities.

TSE-MSDE is a new MR imaging technique similar to diffusion-weighted imaging that has been applied to the evaluation of atherosclerotic plaque in the coronary and carotid arteries, as well as brain metastases.<sup>8,9</sup> TSE-MSDE has also been applied for assessment of the existence of brain metastasis with contrast media.<sup>10</sup> This method takes advantage of a preparative sequence, a diffusion pulse with a very low b-value consisting of 3 nonselective radio-frequency pulses with flip angles of 90–180–90°, and symmetric gradients around the 180° pulse. It causes phase dispersion of blood and CSF spins by using a magnetic field gradient and suppresses any flow signals.<sup>11</sup> TSE-MSDE is able to clearly show only cranial nerves in the cistern with no flow signal.<sup>12</sup> We hypothesized that TSE-MSDE may be able to effectively visualize the trochlear nerve because it can suppress any signals in the cistern. The purpose of our study was to assess visualization of the trochlear nerve in the cistern by using TSE-MSDE.

Received July 31, 2012; accepted after revision September 28.

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This work was supported by a grant-in-aid from the Global COE (Centers of Excellence) Program of the Japan Society for the Promotion of Science.

Paper previously presented at: Annual Meeting of the Japanese Society of Neuro-radiology, Tokyo, Japan, February 2011, and Annual Meeting of the European Society of Neuroradiology, Antwerp, Belgium, September 2011.

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<http://dx.doi.org/10.3174/ajnr.A3403>

## MATERIALS AND METHODS

This protocol was approved by our ethics committee.

### Participants

Participants were 10 healthy young adults (6 men and 4 women; mean age, 24 years; age range, 21–28 years), and 20 trochlear nerves were examined. We obtained informed consent from these volunteers before performing MR imaging. We verbally confirmed that they had never undergone surgery or had any significant or relevant prior medical problems.

### MR Imaging

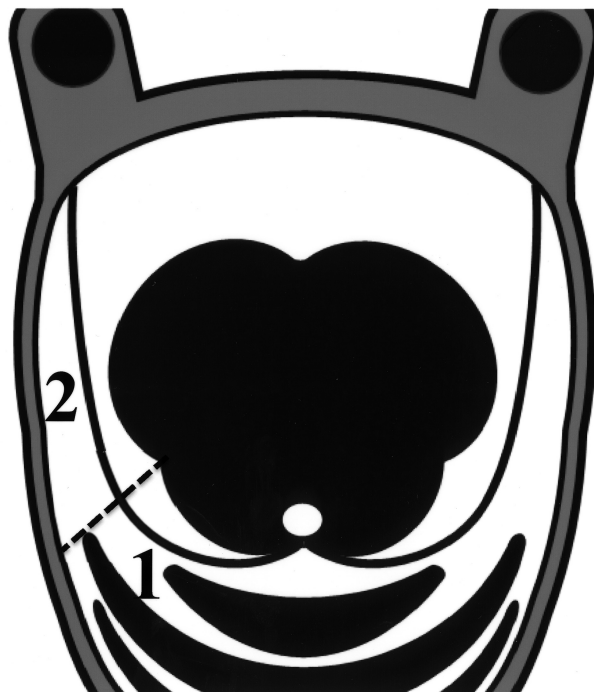
We performed 3 MR imaging sequences for each participant by using a 3T MR imaging unit (Intera Achieva; Philips Healthcare, Best, the Netherlands). We modified the conventional MRC and TSE-MSDE to visualize the trochlear nerve and created HR-MRC and HR-MSDE protocols. In addition to these MR imaging sequences, we also performed BS-MRC, according to a previous study.<sup>13</sup> The imaging parameters were as follows. For HR-MRC, TR was 3000 ms; TE, 287 ms; acquisition voxel size,  $0.30 \times 0.33 \times 0.60$  mm; reconstruction voxel size,  $0.21 \times 0.21 \times 0.30$  mm; NEX, 1; FOV, 150 mm; flip angle,  $90^\circ$ ; number of sections, 80; section thickness, 0.30 mm; coil, sensitivity encoding 8-channel head coil; scan time, 18 minutes 3 seconds; and SAR/head, 0.9 W/kg. For the balanced sequence, TR was 9.0 ms; TE, 3.5 ms; acquisition voxel size,  $0.29 \times 0.30 \times 0.50$  mm; reconstruction voxel size,  $0.29 \times 0.25$  mm; NEX, 1; FOV, 150 mm; flip angle,  $60^\circ$ ; number of sections, 60; section thickness, 0.25 mm; coil, sensitivity encoding 8-channel head coil; scan time, 11 minutes 59 seconds; and SAR/head, 3.2 W/kg. For HR-MSDE, TR was 24 ms; TE, 4 ms; acquisition voxel size,  $0.39 \times 0.38 \times 0.50$  mm; reconstruction voxel size,  $0.31 \times 0.31 \times 0.25$  mm; NEX, 1; FOV, 200 mm; flip angle,  $20^\circ$ ; b-value, 10; number of sections, 120; section thickness, 0.25 mm; coil, sensitivity encoding 8-channel head coil; scan time, 26 minutes 37 seconds; and SAR/head, 0.6 W/kg. These sequences were prescribed in the axial plane, and the scan range was set so that the mesencephalon and cavernous sinuses were included.

### Image Analysis

Two experienced neuroradiologists (A: Y.T. and B: M.K., with 7 and 10 years of experience, respectively) evaluated the MR images and separately determined the visibility of each trochlear nerve.

First, neuroradiologist A evaluated whether the trochlear nerve was identified in full length in the cistern (from the quadrigeminal cistern to the entrance of the cavernous sinus). We classified the visibility of trochlear nerve into 4 grades: “Excellent,” “Good,” “Fair,” and “Not.” A grade of “Excellent” was given if more than 90% of full length was identified; “Good,” if 50%–90% of full length was identified; “Fair,” for 10%–50% of full length; and “Not,” for less than 10% of full length.

Next, we divided the trochlear nerve into 2 segments—the perimesencephalic segment and the tentorial segment—by using a line that links the mesencephalic tegmentum-cerebral peduncle junction to the cerebellar anterior border in the same section (Fig 1).<sup>6</sup> The perimesencephalic segment was defined as the range from the root exit point of the trochlear nerve in the dorsal mesencephalon to the ambient cistern. The tentorial segment was defined as the range from the portion along the cerebellar tentorium to the cavernous sinus. If the nonbranching curvilinear structure was evident in the ambient cistern and along the cerebellar tentorium, it was identified as the trochlear nerve. The visibility of the trochlear nerve in each segment was evaluated by 2



**FIG 1.** Segmentation of the trochlear nerve. The trochlear nerve in the cistern was divided into 2 segments: the perimesencephalic segment and the tentorial segment, by use of the line that links the mesencephalic tegmentum-cerebral peduncle junction to the cerebellar anterior border in the same section. 1. Perimesencephalic segment. 2. Tentorial segment.

**Table 1: Visibility of 20 trochlear nerves in full length**

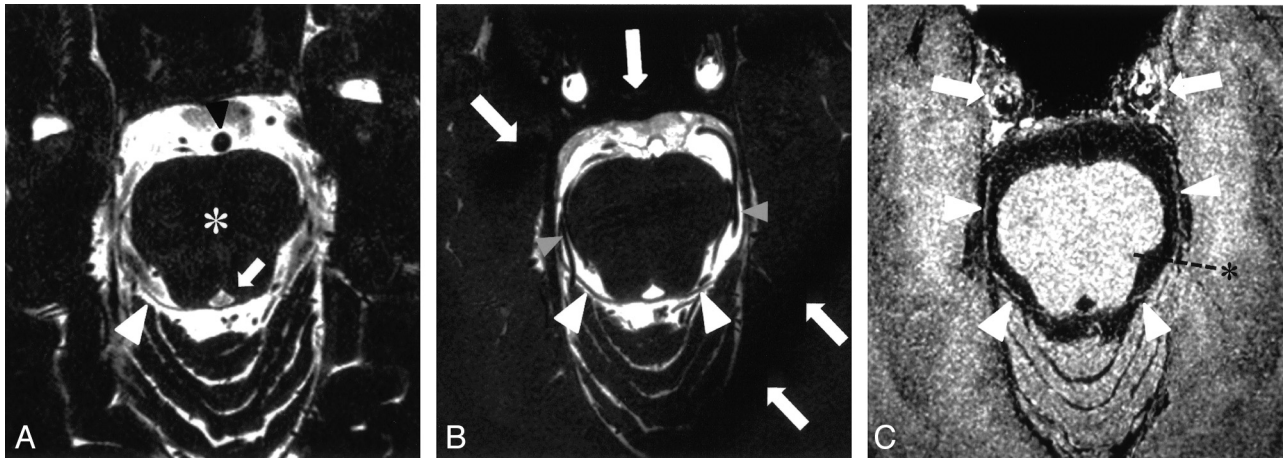
Visibility	HR-MRC	BS-MRC	HR-MSDE
Excellent	6	13	18
Good	5	2	1
Fair	9	4	1
Not	0	1	0

neuroradiologists. We observed all images by using a DICOM viewer (Philips Healthcare) and by paging all sections. The viewers could scroll through the sections and change appropriate window/level magnification. The visibility of each sequence was statistically analyzed by use of the  $\chi^2$  test, and we calculated the  $\kappa$  coefficient between the 2 neuroradiologists for each MR imaging sequence and segment to evaluate the concordance of the findings between them (SPSS, version 16.0; SPSS, Chicago, Illinois).

## RESULTS

### Visibility of the Trochlear Nerve in Full Length

The visibility of the trochlear nerve in full length is summarized in Table 1. Of all 20 trochlear nerves, 6 with HR-MRC, 13 with BS-MRC, and 18 with HR-MSDE were judged as “Excellent” by a neuroradiologist. With HR-MRC, CSF flow-related artifacts and vessels in the cistern and/or cerebellar tentorium tended to prevent the neuroradiologists from identifying the trochlear nerve (Fig 2A). With BS-MRC, vessels in the cistern and the cerebellar tentorium also tended to prevent the neuroradiologists from identifying the trochlear nerve (Fig 2B). HR-MSDE more often visualized the trochlear nerve compared with the other sequences (Fig 2C). The  $\chi^2$  test revealed statistically significant differences among these 3 MR imaging sequences ( $P < .01$ ).



**FIG 2.** MR images of each sequence. *A*, HR-MRC: Perimesencephalic segment of the right trochlear nerve is observed (*white arrowhead*). Marked CSF flow-related artifacts in the cistern are apparent. The basilar artery (*black arrowhead*), midbrain (\*), and cerebral aqueduct (*white arrow*) are noted. *B*, BS-MRC: Bilateral trochlear nerves are apparent in the cistern (*arrowheads*). The bilateral posterior cerebral artery is observed around the trochlear nerve (*gray arrowheads*). Band artifacts are also evident (*white arrows*). *C*, HR-MSDE: Trochlear nerves are visualized as curvilinear structures in full length (*arrowheads*). The line for segmentation (\*) and the carotid artery (*white arrows*) are observed.

**Table 2: Visibility of 20 trochlear nerves in each segment between 2 neuroradiologists**

Segment of the Trochlear Nerve	HR-MRC		BS-MRC		HR-MSDE	
	A	B	A	B	A	B
Perimesencephalic	19	14	19	18	20	20
Tentorial*	7	2	13	14	19	18

A indicates neuroradiologist A; B, neuroradiologist B.

\* Significant differences among 3 MRI sequences by the  $\chi^2$  test ( $P < .01$ ).

**Table 3: Concordance in each MR imaging sequence between 2 neuroradiologists**

Segment of the Trochlear Nerve	$\kappa$ Coefficient		
	HR-MRC	BS-MRC	HR-MSDE
Perimesencephalic	0.286	0.643	—*
Tentorial	0.219	0.659	0.643

\* The  $\kappa$  coefficient could not be calculated because both neuroradiologists evaluated the trochlear nerve as “visible” in all cases.

### Visibility of the Trochlear Nerve in the Perimesencephalic Segment

The visibility of the trochlear nerve in the perimesencephalic segment is summarized in Table 2. HR-MRC, BS-MRC, and HR-MSDE had approximately equal trochlear nerve visualization performance. For neuroradiologist B, the  $\chi^2$  test revealed statistically significant differences among these 3 MR imaging sequences ( $P = .02$ ).

### Visibility of the Trochlear Nerve in the Tentorial Segment

The visibility of the trochlear nerve in the tentorial segment is summarized in Table 2. As with the evaluation in full length, CSF flow-related artifacts, vessels in the cistern, and cerebellar tentorium in HR-MRC tended to prevent both neuroradiologists from identifying the trochlear nerve (Fig 2A). Vessels in the cistern and cerebellar tentorium in BS-MRC also tended to prevent both neuroradiologists from identifying the trochlear nerve (Fig 2B). HR-MSDE more often visualized the trochlear nerve compared with the other sequences (Fig 2C). For both neuroradiologists A and B, the  $\chi^2$  test revealed statistically significant differences among these 3 MR imaging sequences ( $P < .01$ ).

### Visibility Concordance between 2 Neuroradiologists

The concordance of visibility of the trochlear nerve between the 2 neuroradiologists is summarized in Table 3. There were high concordances in BS-MRC and HR-MSDE ( $\kappa = 0.643$ – $0.659$ ). In the tentorial segment of HR-MSDE, the  $\kappa$  coefficient could not be calculated because both neuroradiologists evaluated the trochlear nerve as “visible” in all cases. In HR-MRC, there was a low concordance between the 2 radiologists.

## DISCUSSION

Our study demonstrates that we can almost always observe the cisternal portion of the trochlear nerve by using HR-MSDE. The trochlear nerve, the diameter of which ranges from approximately 0.3 to 0.9 mm, is the thinnest of all cranial nerves.<sup>13</sup> Moreover, it has a complex 3D course around the midbrain, and many arteries and veins, as well as the cerebellar tentorium, are in close proximity to the nerve.<sup>4–7</sup> Thus, it has been difficult to identify the trochlear nerve by using a variety of even HR MR imaging sequences. We demonstrated that HR-MSDE was significantly superior to both HR-MRC and BS-MRC in visualizing the trochlear nerve, with high concordance between 2 neuroradiologists.

The perimesencephalic segment of the trochlear nerve was generally well identified on all MR images used. This is probably because of the course of the nerve around the midbrain. The trochlear nerve originates from the root exit zone in the dorsal pontomesencephalic junction and runs a curved course that differs from the course of the vessels in the perimesencephalic cistern. In contrast, the tentorial segment of the trochlear nerve tended to be obscured on the MRC images, as it runs along the tentorial edge and is parallel to the vessels in its tentorial segment. Therefore, the trochlear nerve may be difficult to differentiate from the tentorial edge and/or vessels on MRC images because both nerves and vessels are rendered with low intensity.

TSE-MSDE provides 3D T1 contrast images that can nearly entirely suppress flow signals by using a preparation pulse. Previous reports<sup>8–12</sup> have discussed TSE-MSDE regarding the atherosclerotic change in vessels, the existence of brain metastasis, and focal deformation of nerves by vessels in neurovascular compression syndrome. In our study, we obtained HR images with TSE-MSDE (ie, HR-MSDE) to visualize the trochlear nerve. The flow signals from vessels and CSF were well suppressed, and only the

cranial nerves were clearly visualized in the cistern. In addition, the signal of the cerebellar tentorium was also suppressed because its low T1 contrast was the same as that of CSF. Thus, the trochlear nerve was well visualized not only in its perimesencephalic segment but also in its tentorial segment. Because the oculomotor nerve and the trigeminal nerve are much thicker than the trochlear nerve, these cranial nerves were clearly visualized in the same scan range. As MR imaging contrast media can be used in conjunction with HR-MSDE, we may in the future be able to visualize actual lesions causing trochlear nerve paralysis by using this method and applying it to clinical cases.

MRC is generally an adequate method to delineate cranial nerves and related vessels.<sup>14</sup> The trochlear nerve is so thin, however, that much thinner sections are required to visualize it than are routinely acquired. If very thin sections are acquired, then prominent flow-related artifacts will occur as a result of CSF, and this mechanism creates a significant problem in the observation of the nerves and vessels. Indeed, the trochlear nerve was poorly identified on HR-MRC images, especially in its tentorial segment.

In general, 3D constructive interference in steady state and fast imaging employing steady-state acquisition visualize the cranial nerves well, such as the oculomotor, trigeminal, abducens, facial, auditory, and lower cranial nerves, but the trochlear nerve is an exception.<sup>15–21</sup> Cranial nerves that penetrate the cavernous sinus, such as the oculomotor, trochlear, trigeminal, and abducens nerve, can be visualized by 3D constructive interference in steady state.<sup>21</sup> However, it has been difficult to visualize the trochlear nerve in its cisternal segment. Choi et al<sup>13</sup> reported that the trochlear nerve can be clearly visualized with HR 3D balanced turbo-field echo. We applied this method in our MR imaging unit and obtained BS-MRC. It is easier to identify the trochlear nerve with BS-MRC compared with HR-MRC because there is decreased influence of flow-related artifacts from CSF.<sup>22</sup> However, band artifacts often occur in the peripheral area of the cistern on BS-MRC images, and there is a scan range limit. Thus, we can only observe the central area in the area of interest, and the observable area is narrow.

The major limitation of our study was the long scan time required. It took approximately 30 minutes for HR-MSDE; therefore, the scan time is so long that this sequence is not yet of practical use. In our study, we acquired 120 sections in HR-MSDE to visualize a thin nerve, the trochlear nerve, with HR and high signal-to-noise ratio. If the number of sections is reduced, then signal-to-noise ratio decreases, and it may become impossible to identify the trochlear nerve. A much shorter scan time for this sequence for practical use should be achievable through the improvement of sequence parameters or the use of a 7T MR imaging unit in the future. Decreased scan time would also allow application of this method in pediatric cases (eg, congenital palsy of the superior oblique muscle). In our study, however, the scan time was not able to be reduced anymore; therefore, it is impossible to apply this method to pediatric cases at present. We also acknowledge that our BS-MRC was a slightly different sequence from the originally reported one, as we had to adjust parameters for use on a different MR imaging machine.

## CONCLUSIONS

HR-MSDE is clearly able to visualize the trochlear nerve and, in general, has a better ability to delineate the trochlear nerve compared with other MR imaging sequences. However, the scan time is so long that it is not yet feasible for routine clinical use.

Disclosures: Masafumi Kanoto—RELATED: Grant: Grant-in-aid from the Global COE (Centers of Excellence) Program of the Japan Society for the Promotion of Science.\* (\*Money paid to institution.)

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