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T2* Mapping with Background Gradient Correction Using Different Excitation Pulse Shapes

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ABSTRACT

SUMMARY: Background gradients induced by magnetic susceptibility variations near air-filled cavities in the brain cause signal-intensity loss in gradient-echo images and shorten T2* considerably. With a correction method in which the exponential decay is restored with section-profile-dependent correction factors, parts of the signal intensity can be recovered. While uncorrected T2* values drop by 20% at a gradient strength of 75 μ T/m, with correction and exponential excitation pulses, this boundary is pushed to 220 μ T/m.

A ccurate T2* measurement is important for a variety of applications. In Parkinson disease studies, it is used to gain insight into the iron content in the substantia nigra.¹ It is also required for a quantitative analysis of the oxygen distribution in the brain.² The sensitivity of T2* to variations in oxygen saturations is exploited in functional activation studies.³

Local macroscopic magnetic susceptibility differences, particularly near air-tissue interfaces, can severely reduce T2* values. Especially at high field strengths, image quality is degraded in large parts of the brain.

Recently, a method has been described for correcting the signal intensity for deviations from monoexponential decay by using exponential excitation pulse shapes.⁴ The deviation of the signal intensity from undisturbed exponential decay is corrected with the help of prefactors calculated from the temporal profile of the excitation pulse and the simultaneously measured local background gradient strength. This correction extends the information content of the T2* map in the affected areas, yet at the price of a more imprecise section profile.

The aim of the current study was to compare 3 different pulse

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shapes (sinc-Gauss, sinc, and exponential) and to determine the susceptibility gradient strength up to which T2* mapping yields reliable results.

TECHNIQUE

With an excitation pulse time profile A and a section-selection gradient strength G_s , the resulting signal intensity in the presence of a background susceptibility gradient G_{susc} is described by^{4,5}

1)
$$S(TE) \propto A\left(\frac{G_{\text{susc}}}{G_s} \cdot TE\right) \cdot e^{-TE/T2^*},$$

where G_{susc} is assumed to be linear and perpendicular to the selected section. Thus, the signal-intensity decay is not necessarily exponential any more but rather influenced by the temporal shape of the pulse. The weighting, in turn, depends on the susceptibility gradient strength as well as on the section-selection gradient in a way that is different for each pulse shape.

A gradient map in the through-plane direction is required to obtain the correction factor 1/A. For a distance between voxels Δx , the gradient strength G_{susc} is obtained from the phase difference $\Delta \phi$ of the first and second echoes⁴:

2)
$$G_{\text{susc}} = \frac{\Delta \phi}{\gamma \cdot \Delta x \cdot (TE_2 - TE_1)} \, .$$

Across a thicker section, a given susceptibility gradient effects a larger range of magnetic field values and thus signal intensity loss, which is why the correction method generally works better for thinner sections. The phase map was calculated from real and imaginary data acquired simultaneously with the magnitude data.

Exponential and sinc-shaped time profiles were defined as⁵

)
$$A_{\text{expo}}(t) = \exp\left(-4 \frac{|G_{\text{susc}}|}{G_{\text{s}}} \cdot \frac{t}{p/2}\right),$$

and

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FIG 1. Left column: graphic representations of the pulse shapes. Center column: $T2^*$ values of a homogeneous phantom at different gradient strengths. Error bars indicate the SD of different $T2^*$ values measured in voxels experiencing the same gradient strength. Right column: SNR at different gradient strengths (TE = 48 ms). Row *A*, Exponentially shaped pulse. Row *B*, Sinc-shaped pulse. Row *C*, Sinc-Gauss–shaped pulse.

4)

$$A_{\rm sinc}(t) = \operatorname{sinc}\left(2\pi \frac{|G_{\rm susc}|}{G_{\rm s}} \cdot \frac{t}{p/2}\right) \cdot \cos\left(\frac{\pi}{2} \frac{|G_{\rm susc}|}{G_{\rm s}} \cdot \frac{t}{p/2}\right),$$

with a pulse duration *p* (Fig 1*A*, -*B*). The cosine term acts as a filter to achieve a smooth excitation spectrum. The third pulse with an optimized sinc-Gauss shape, which is used by default in fast-field-echo imaging protocols, was approximated numerically (Fig 1*C*).

Magnitude, real and imaginary images in transverse orientation were acquired with a 3T Achieva scanner (Philips, Best, the Netherlands) by using an 8-channel head coil. A multi-gradientecho sequence with 10 evenly spaced echoes was used to acquire 40 sections (TE₁ = 3 ms, Δ TE = 5 ms, TR = 2055 ms, rapid flyback, FOV = 184 × 132 mm², in-plane resolution = 2 × 2 mm², section thickness = 3 mm, reconstructed matrix = 112 × 112, flip angle = 60°, total scan time = 3 minutes, 5 seconds). Apart from the scanner-default sinc-Gauss–shaped excitation pulse, sinc or exponentially shaped pulses could be selected. The respective values for the pulse duration *p* and the section selection gradient *G*_s were 2.11 ms, 11,289 μ T/m (sinc-Gauss), 2.78 ms, and 11,274 μ T/m (sinc and exponential). Imaging was performed on a spherical homogeneous gel phantom consisting of 1.75% agar dissolved in a 0.9% sodium chloride solution doped with 0.11 mmol/L of gadolinium diethylene triamine pentaacetic acid. Although in vivo susceptibility gradients are primarily due to air cavities, similar gradient strengths in the phantom can be induced by using a small piece of metal positioned at the bottom of the phantom. Additionally, images of 4 volunteers were acquired (3 men, 32.5 ± 15.2 years of age).

The weighting of the exponentially decaying data with the pulse profile was eliminated by using correction factors according to equations 3 and 4 and the numerically approximated sinc-Gauss shape. A voxelwise monoexponential fit of the corrected data was then performed to obtain T2* maps. All calculations were done in Matlab 7.9 (MathWorks, Natick, Massachusetts).

DISCUSSION

In Fig 1, T2* values are plotted against the corresponding susceptibility gradient strengths for a cuboid volume of interest in the phantom where the background gradient exhibits strong variation over several sections. Uncorrected T2* values drop by 20% at a gradient strength of 75 μ T/m for sinc-shaped pulses, 63 μ T/m for sinc-Gauss–shaped pulses, and 34 μ T/m for exponential pulses. Data acquired with the sinc-Gauss–shaped pulse can be



FIG 2. A, Susceptibility gradient map. Also shown are uncorrected (top) and corrected (bottom) T2* maps of a section of a homogeneous phantom with exponential (B), sinc (C), and sinc-Gauss (D) excitation pulses.



FIG 3. In vivo T2* maps of 2 sections. From left to right: smoothed through-plane gradient map; uncorrected T2* map acquired with an exponential pulse; corrected maps with exponential, sinc, and sinc-Gauss pulses.

corrected with the applied method for gradient strengths up to approximately 100 μ T/m with a deviation of <20%. In the presence of stronger background gradients, the resulting T2* values are not reliable. With the same 20% criterion, data acquired with the sinc-shaped pulse can be corrected up to gradients of 175 μ T/m, whereas for exponentially shaped pulses, the 20% boundary is reached at 220 μ T/m. With exponential pulses, even higher field gradients can be corrected to some extent.

Corrected values spread more than uncorrected values due to

the additional source of uncertainty when a measured susceptibility gradient map is used. Also shown in Fig 1 is the SNR at different gradient strengths at TE = 48 ms. SNR was calculated as the mean of the signal intensity at a given susceptibility gradient strength divided by its SD. For each of the pulses, SNR drops significantly at gradient strengths where corrected T2* values start to spread and become unreliable. At low gradients, SNR is higher for sinc and sinc-Gauss pulses than for exponential pulses, indicating that such pulses might be the better choice in this case. Figure 2 shows the effect of the different pulse shapes on phantom T2* maps. Compared with the other 2 pulse shapes, an exponentially shaped pulse enhances susceptibility effects in the uncorrected T2* map, because the exponent of the time profile represented in equation 3 is added to the exponent of the pure T2* decay in equation 1, therefore lowering the effective time constant of the decay. However, data acquired with the exponential pulse can be corrected for higher susceptibility gradient strengths when the sinc and the sinc-Gauss corrections have already failed. Still, if only very weak background gradients interfere with the measurement, a sinc-shaped pulse with its more rectangular section profile can be better corrected for. When using exponential pulses, a sufficient section gap and interleaved acquisition mode should be chosen.

The superior performance of exponentially shaped pulses can be explained as follows: The time profile of the numerically optimized sinc-Gauss pulse can only be approximated in the correction routine, whereas the analytic representation of the other 2 pulses is accurate. Both the sinc-Gauss and the sinc-shaped pulses show zero crossings in their time profiles, which result in increased signal-intensity losses compared with the exponential pulse. From equations 1, 3, and 4, and the numeric representation of the sinc-Gauss profile, critical values for G_{susc} can be determined where the signal intensity has dropped to a certain value. At TE = 48 ms, an 80% signal intensity loss is reached at susceptibility gradients of 131 μ T/m (exponential), 43 μ T/m (sinc), and 118 μ T/m (sinc-Gauss), respectively.

From the analysis of phantom data, it can be seen that a true plateau cannot be maintained for any of the tested pulse shapes. However, the information in the T2* map that is accessible for diagnostic evaluation can be extended considerably by using an exponentially shaped excitation. Especially regions close to air-filled cavities in the orbitofrontal cortex or in the temporal lobes

now become visible for inspection, even though the absolute values might not be quite accurate (Fig 3).

At 3T, typical gradient values of $300-500 \ \mu$ T/m occur in extended areas.^{5,6} We observed in vivo background gradients up to approximately 400 μ T/m. With the help of exponential pulses and a correction routine that accounts for the modified T2* decay as described above, large parts of the T2* map can be recovered, even at such field variations, contrary to the other tested pulse shapes. Exponentially shaped pulses thus appear to be favorable for in vivo measurements. Their somewhat more imprecise Lorentzian section profile can be compensated sufficiently by choosing an interleaved acquisition scheme and a small gap between sections.

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