Intraoperative Conebeam CT for Assessment of Intracochlear Positioning of Electrode Arrays in Adult Recipients of Cochlear Implants

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AJNR Am J Neuroradiol 2018, 39 (4) 768-774
doi: https://doi.org/10.3174/ajnr.A5567
http://www.ajnr.org/content/39/4/768
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ABSTRACT

BACKGROUND AND PURPOSE: Intraoperative conebeam CT has been introduced into the operating room and provides quick radiologic feedback. This study aimed to investigate its utility in the assessment of the positioning of the electrode array after cochlear implantation.

MATERIALS AND METHODS: This was a retrospective study of 51 patients (65 ears) with intraoperative imaging by conebeam CT (O-arm) after cochlear implantation between 2013 and 2017. Correct placement into the cochlea was immediately identified. Positioning assessments were later analyzed with OsiriX software.

RESULTS: Intraoperative imaging was quickly performed in all cases. No misplacement into the vestibule or semicircular canals was found. A foldover of the implanted array was identified in 1 patient. Secondary analysis by 2 raters showed excellent agreement on insertion depth angle (intraclass correlation coefficient = 0.96, \( P < .001 \)) and length of insertion of the electrode array (intraclass correlation coefficient = 0.93, \( P = .04 \)) measurements. The evaluation of the number of extracochlear electrodes was identical between the 2 raters in 78% of cases (Cohen \( \kappa = 0.55, P < .001 \)). The scalar position was inconsistent between raters. When we compared O-arm and high-resolution CT images in 14 cases, the agreement was excellent for insertion depth angle (intraclass correlation coefficient = 0.97, \( P < .001 \)) and insertion length (intraclass correlation coefficient = 0.98, \( P < .001 \)), good for the number of extracochlear electrodes (Cohen \( \kappa = 0.63, P = .01 \)), but moderate for the scalar position (Cohen \( \kappa = 0.59, P = .02 \)).

CONCLUSIONS: Intraoperative conebeam CT using the O-arm is a safe, rapid, easy, and reliable procedure to immediately identify a misplacement or foldover of an electrode array. The insertion depth angle, insertion length, and number of electrodes inserted can be accurately assessed.

ABBREVIATIONS: CBCT = conebeam CT; HRCT = high-resolution CT; ICC = intraclass correlation coefficient

The cochlear implant is an electronic medical device for rehabilitation of profound hearing loss. When implanted into the cochlea, the electrode array stimulates the spiral ganglion cells with encoded electrical impulses; therefore, correct placement of the array is essential for a well-functioning cochlear implant. Imaging examination after implantation with, for example, radiography and fluoroscopy or high-resolution CT (HRCT) is mandatory in most centers to verify correct placement of the electrode array intra- or postoperatively, in particular, assessment of the insertion depth and the number of electrodes inserted.\(^1,2\) Radiography and fluoroscopy, typically using a transorbital or modified Stenvers view, were initially applied to cochlear implantation,\(^3,4\) but their major limitations were poor image resolution of the intracochlear structures and the lack of 3D views. Consequently, some cases of misplacement of the array into the semicircular canal or vestibule could not be distinguished intraoperatively.\(^5,6\) Thus, in many medical centers, HRCT, which provides better resolution and presents sagittal, axial, and coronal views, became the routine imaging procedure after cochlear implantation and before discharge. Nevertheless, the HRCT platform is fixed, and this imaging cannot be performed in the operating room like radiography and fluoroscopy.
Conebeam CT (CBCT), which was primarily developed for dental and maxillofacial imaging, is now used in cochlear implantation. In contrast to conventional spiral HRCT, which uses a narrow fan-shaped beam requiring multiple rotations around the patient to create a volume of data, CBCT only requires a single rotation of a cone-shaped beam that includes the whole FOV. The x-ray source and the flat panel detector rotate around a fixed point in the center of the ROI. CBCT can provide higher spatial resolution and dynamic range than HRCT. Other advantages of CBCT include less intense metallic artifacts and lower radiation exposure than conventional multislice HRCT.9 During the past 10 years, CBCT has been developed as an alternative to HRCT in temporal bone imaging.10-13 Several studies have shown high sensitivity and specificity of nonmobile CBCT in the assessment of the scalar position of the electrode array in temporal bone specimens from cadavers.14-17 Furthermore, CBCT can be a mobile platform that can be used in the operating room. The purpose of this study was to assess the feasibility, reliability, and utility of mobile CBCT in the assessment of positioning of an electrode array in the operating room, immediately after cochlear implantation.

**MATERIALS AND METHODS**

All participants provided written informed consent allowing retrospective analysis of their data (CNIL No. 2040854).

**Patients**

A retrospective review was conducted on 51 patients (65 ears) who underwent cochlear implantation in a French tertiary medical center between July 2013 and March 2017 (Tables 1 and 2). An intraoperative radiologic evaluation (O-arm imaging system; Medtronic, Minneapolis, Minnesota) was performed after cochlear implantation and before the patients awoke from the anesthesia. Their medical records, including type of implant, surgical details, and radiologic images, were collected.

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**Table 1: Population characteristics (N = 51 patients)**

<table>
<thead>
<tr>
<th>Demographics</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Age (mean ± SEM) (range) (yr)</td>
<td>53 ± 7.1 (20–87)</td>
</tr>
<tr>
<td>Sex (M/F)</td>
<td>24:27</td>
</tr>
<tr>
<td>Anatomy</td>
<td></td>
</tr>
<tr>
<td>Normal</td>
<td>64 ears</td>
</tr>
<tr>
<td>Major aplasia</td>
<td>1 ear</td>
</tr>
<tr>
<td>Implanted side</td>
<td></td>
</tr>
<tr>
<td>Left</td>
<td>18 patients</td>
</tr>
<tr>
<td>Right</td>
<td>19 patients</td>
</tr>
<tr>
<td>Bilateral</td>
<td>14 patients</td>
</tr>
</tbody>
</table>

Note: —SEM indicates standard error of the mean.

**Table 2: Device characteristics (N = 65 devices)**

<table>
<thead>
<tr>
<th>Devices</th>
<th>Proprietary Name</th>
<th>O-arm</th>
<th>HRCT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Advanced Bionics (16 electrodes)</td>
<td>Helix 1</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>Cochlear (22 electrodes)</td>
<td>Mid-Scala</td>
<td>3</td>
<td></td>
</tr>
<tr>
<td>Perimodiolar</td>
<td>CI 24, CI 512</td>
<td>12</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>CI 532</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>Straight</td>
<td>CI 422, CI 522</td>
<td>31</td>
<td>9</td>
</tr>
<tr>
<td>MED-EL (12 electrodes)</td>
<td>Flex 28</td>
<td>13</td>
<td>3</td>
</tr>
<tr>
<td>Oticon (20 electrodes)</td>
<td>Evo</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Standard</td>
<td>1</td>
<td></td>
</tr>
</tbody>
</table>

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**Surgical Procedures**

The operation was performed by the same senior otologist. Cochlear implantation was performed in all cases using a minimally invasive protocol, with 4 brands of implant devices (Advanced Bionics, Valencia, California; Cochlear, Lane Cove, Australia; MED-EL, Innsbruck, Austria; and Oticon Medical, Vallauris, France).

**Radiologic Examinations and Analysis**

In 14 patients who had implantation on their second side, the electrode position of the first side was assessed on preoperative HRCT images (0.6-mm thickness), performed in the neuroradiologic center, using a Discovery CT 750 HD scanner (GE Healthcare, Milwaukee, Wisconsin). This assessment allowed a comparison of the imaging between HRCT and CBCT for the same implant, without an additional radiologic examination. The mean CT dose index of HRCT for these 14 patients was 91 ± 10.4 mGy, and the dose-length product was 605 ± 57.2 mGy · cm².

CBCT was performed immediately after closure of the incision using the O-arm. The tube voltage was 120 kV, with a 12-mA charge at the terminals. This intraoperative imaging platform provides 2D fluoroscopic imaging and a 360° scan resulting in 3D multiplanar views. Fluoroscopy must be performed before the 3D acquisitions to verify the optimum positioning of the targeted ear in the gantry. The 3D imaging volume was cylindrical (15-cm height × 20-cm diameter; 512 × 512 × 192 resolution), which was large enough to simultaneously detect both ears in 1 scan. After each scan, the 3D-MPR was automatically generated and 3 windows with planar images (coronal, sagittal, and axial) were immediately shown with free 3D rotation (Fig 1A). This process provided a slice thickness of 0.83 mm in the axial plane and 0.415 mm in the coronal and sagittal planes. One 360° rotation of the x-ray tube took 13 seconds. The CT dose index in the 51 patients was 12 ± 2.6 mGy, and the dose-length product was 200 ± 53.4 mGy · cm².

The patients underwent the operation on a radiolucent carbon fiber surgical table in a dedicated operating room with x-ray protection. The installation and scanning with the O-arm were performed by the surgeon. The duration from the entrance of CBCT into the operating room to the completion of scanning was timed. The CBCT images were assessed by the surgeon immediately after scanning to eliminate a misplacement of the electrode array into the vestibule or semicircular canals or a foldover of the intracochlear array.

The radiologic images were later analyzed by 2 specialists experienced in cochlear implant imaging. The depth angle and the length of insertion, the number of extracochlear electrodes, and the scalar position of the array at 180° and 360° depth were assessed using OsiriX Imaging Software (http://www.osirix-viewer.com) as previously described. Briefly, the reconstruction plane for the evaluation of the electrode position was the midmodiolar plane obtained with the curved multiplanar reconstruction (3D Curved MPR Viewer in OsiriX). This plane was defined as a 3D Bézier path along the electrode array. Once the path was defined by the selection of all the single electrodes, the array was straightened and visible in the Curved MPR Viewer window. Then, the electrode array can be visualized in a dynamic series of...
the midmodiolar section of the cochlea, and the raters estimated the localization, scala tympani, scala vestibuli, or intermediate position on the basis of the theoretic positions of the scala for electrodes positioned at 180° and 360°. Assessment was performed independently and was timed. In cases in which there was a discrepancy in the number of extracochlear electrodes or in the scalar position between independent analyses, a coassessment was then performed by both raters to obtain a result with which they both agreed.

**Statistical Analysis**

Data are presented as mean ± standard error of the mean. Interrater reliability was calculated using the intraclass correlation coefficient (ICC) for the quantitative variables insertion depth angle.
and insertion length or the Cohen κ for the categoric variables electrode number and scalar position. The reliability of the electrode number with the total number of cases was calculated with the weighted data based on the electrode number of the implant device. Paired t tests or Fisher exact tests were applied for comparison of variables. The criterion for statistical significance was set at $P < .05$, 2-tailed. R statistical and computing software (http://www.r-project.org) was used.

**RESULTS**

**Analysis of Intraoperative Electrode Positioning Using the O-Arm**

The mean duration of installation and scanning was 5.4 ± 1.2 minutes. In this series, misplacement into the vestibule or semicircular canals was eliminated intraoperatively. In 1 case with major aplasia of the ear, the difficulty of implantation was increased by malformation of the middle ear, but the intraoperative images confirmed the correct position of the array. In another case in which a novel design of the array (CI 532; Cochlear, Lane Cove, Australia) was implanted, a foldover of the inserted array was observed (Fig 1B–D). This patient was re-implanted with a CI 522 (Cochlear), and the new electrode array was inserted correctly with an insertion depth angle of 399° and insertion length of 22.4 mm (Fig 1E–G). The case of foldover was excluded from the OsiriX analysis.

**Assessment of Electrode Positioning**

Independent assessments were performed by 2 raters for 64 ears with O-arm data, using the MPR viewer of OsiriX. The mean time for analysis was 3.1 ± 1.1 minutes for one rater and 3.7 ± 0.4 minutes for the other. There was an excellent agreement between raters for the depth angle of insertion (ICC = 0.96, $P < .001$) and insertion length (ICC = 0.93, $P = .04$), with a non-statistically significant difference between raters of 0.8° ± 0.8° for insertion depth angle and 0.6 ± 0.1 mm for insertion length (Table 3).

Because the intracochlear electrodes were not clearly shown on O-arm images (Fig 2G, -H), apart from those of the MED-EL implant, which has only 12 electrodes (Fig 2E, -F), the extracochlear electrodes that were more clearly identified were counted. Their numbers were assessed identically between the 2 raters in 50 ears (78%, Cohen κ = 0.53, $P < .001$), and the identical rates among the different types of arrays did not show a statistically significant difference (Table 4). Regarding the scalar position of the electrodes, initial assessment was the same between raters in only 34/64 ears (53%) at 180° and 20/46 ears (43%) at 360°, with

![Figure 2](http://www.ajnr.org)

**Table 3: Insertion depth angle and length of insertion of the electrode array—results from 2 raters using O-arm data**

<table>
<thead>
<tr>
<th>Implant</th>
<th>Rater</th>
<th>Depth Angle (°)</th>
<th>Length (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Advanced Bionics (12)</td>
<td>A</td>
<td>384 ± 28.8</td>
<td>19.5 ± 1.02</td>
</tr>
<tr>
<td>Cochlear (perimodiolar)</td>
<td>B</td>
<td>389 ± 27.7</td>
<td>19.5 ± 0.96</td>
</tr>
<tr>
<td>Cochlear (straight)</td>
<td>A</td>
<td>357 ± 10.1</td>
<td>18.8 ± 0.71</td>
</tr>
<tr>
<td>Cochlear (straight)</td>
<td>B</td>
<td>360 ± 9.5</td>
<td>18.6 ± 0.79</td>
</tr>
<tr>
<td>MED-EL (n = 13)</td>
<td>A</td>
<td>425 ± 12.9</td>
<td>22.1 ± 0.47</td>
</tr>
<tr>
<td>MED-EL (n = 13)</td>
<td>B</td>
<td>427 ± 13.4</td>
<td>22.3 ± 0.47</td>
</tr>
<tr>
<td>Oticon (n = 3)</td>
<td>A</td>
<td>500 ± 30.0</td>
<td>24.1 ± 0.90</td>
</tr>
<tr>
<td>Oticon (n = 3)</td>
<td>B</td>
<td>502 ± 30.0</td>
<td>24.4 ± 0.93</td>
</tr>
</tbody>
</table>

*Values are mean ± standard error of the mean.

**DISCUSSION**

Misplacement of electrode arrays into the vestibule or semicircular canals or foldover of inserted arrays has been reported in about 0.2%–1% of patients18,19-21 and needed to be surgically corrected. Electrophysiologic measurements, such as impedance or neural
inner ear. If HRCT or CBCT is performed as routine post-tomy site and thus may provoke more bleeding or damage in the between the first surgery and revision increases the importance of lost the optimum timing for revision surgery because the delay implantation, and then confirmed by HRCT. These patients have suspected at the first mapping, generally about 2–4 weeks after fluoroscopy, a misplacement outside the cochlea might only be foldover of the array, but intraoperative electrophysiologic measurement. In the present study, 1 patient presented with a misplacement to verify the normal function of the electrode array; however, some intraoperative electrophysiologic measurements have been reported to be normal or near-normal in cases of misplacement to the cochlea might only be suspected at the first mapping, generally about 2–4 weeks after implantation, and then confirmed by HRCT. These patients have lost the optimum timing for revision surgery because the delay between the first surgery and revision increases the importance of tissue repair and fibrosis around the round window or cochleos- tomy site and thus may provoke more bleeding or damage in the inner ear. If HRCT or CBCT is performed as routine post- operative imaging and a misplacement is reported, an additional anesthetic procedure is required for the revision surgery. Furthermore, for recipients who are children, postoperative HRCT is not a routine imaging procedure in many centers and sometimes is a complex procedure requiring sedation and special care. Therefore, intraoperative imaging is very useful and could be indicated at least for individuals who present a risk for a challenging operation because of inner ear malformations and pathologic narrow- ing or obstruction of the cochlear scala in the case of meningitis, trauma, or otosclerosis.

CBCT by the O-arm is designed for intraoperative use, with a radiolucent carbon fiber surgical table in a dedicated operating room with X-ray protection and can be performed before closing the incision using a sterile tube drape. Even though this version of the O-arm software could not realize a maximum intensity projection on its platform, which can rebuild the entire electrode array, a function of free 3D rotation was provided and was very helpful for careful assessment of array positioning. Because of the easy manipulation with the O-arm, the installation, scanning, and assessment of the electrode array can be performed by the surgeon when the protocol is established. In this study, the performance of the O-arm in the operating room was successfully and quickly realized in all cases. In addition, the lower radiation dose compared with HRCT makes it a safer imaging technique.

With advanced software for DICOM such as OsiriX, which has been approved as a reliable and rapid method for assessing radiologic imaging, a more detailed positioning assessment of the electrode array can be realized in the operating room and can give timely feedback to the surgeon. In this series, the insertion depth angle and the length of insertion of the electrode array were assessed promptly (~3–4 minutes) and showed excellent agreement between the raters’ independent assessments. These results also showed excellent agreement with those based on HRCT im-
ages, which is the most common imaging procedure and is considered the criterion standard postoperative protocol for the evaluation of electrode arrays in adults. For electrode counting, there was also good agreement between raters, even though it was difficult to clearly distinguish the electrodes near the round window or cochleostomy on O-arm images, especially for arrays with a high number of electrodes (Fig 2); however, the accuracy of electrode counting by the O-arm was still acceptable compared with HRCT. Consequently, O-arm imaging can be considered a reliable tool for assessing the electrode array position in the cochlea in current practice.

Besides correct placement in the cochlea, translocation into the scala vestibuli is increasingly being studied because it might be associated with poor speech performance.27 In this series, the calculated positioning was difficult to evaluate on O-arm images and a poor interrater agreement was found, whereas other studies have reported more accurate identification of the scalar position.16,17,28,29 This difference might be explained by the technologic differences between mobile and fixed CBCT equipment, such as the i-CAT 3D Imaging System (Imaging Sciences International, Hatfield, Pennsylvania), ILUMA Ultra Cone Beam CT Scanner (IMTEC Imaging, Ardmore, Oklahoma), and NewTom 5G or NewTom VGI CBCT scanner (NewTom, Verona, Italy).13,14,16 Furthermore, analysis by a senior neuroradiologist or with coregistration of preoperative and postoperative images could give a more accurate assessment of the scalar position,16,28,30–33 but this takes a long time and is not feasible for current intraoperative use. Finally, up to now, lack of diagnosis of a translocation is not of primary importance because it is not an indication for re-insertion of the array.

CONCLUSIONS
The O-arm is an imaging platform with mobility, rapid installation, quick scanning, intraoperative use, and low radiation dose. It provides reliable image quality for eliminating misplacement of electrode arrays into the vestibule or semicircular canals or foldover of the inserted array; for measuring the insertion depth and length of insertion; and for counting the number of electrodes inserted, which makes it a practical radiologic technique for assessment of electrode array positioning in the operating room. This is particularly useful for patients in a 1-day operation and in the case of a challenging operation. This device could potentially be combined with navigation or robotic systems. It could also be shared by different disciplines, such as neurosurgery and orthopedics; this feature makes it a valuable piece of equipment in the operating room.

ACKNOWLEDGMENTS
We thank Haoyue Tan for her assistance with statistical analysis and Colin Woodham for language editing.

Disclosures: Olivier Sterkers—UNRELATED: Consultancy: Medtronic, Comments: monitoring of the facial nerve.

REFERENCES